Roll No.

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## August/September 2022 B.Tech. (ENC) IV SEMESTER Theory of Signal System (ECP-406)

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Time : 3 Hours]

[Max. Marks: 75

Instructions :

- 1. It is compulsory to answer all the questions (1.5 marks each) of Part-A in short.
- 2. Answer any four questions from Part-B in detail.
- 3. Different sub-parts of a question are to be attempted adjacent to each other.

## PART-A

1. (a) State the two properties of unit impulse function.

(1.5)

(b) Determine whether the following signals is energy or power signal. Also calculate its energy and power

$$x(t) = e^{-2t} u(t). (1.5)$$

(c) What is the overall impulse response h(t) when two systems with impulse response  $h_1(t)$  and  $h_2(t)$  are connected in :

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	(b)	(a)		(j)	<b>(i)</b>	(h)	(g)	Ð	(e)	(d)	
1. $x(t-1)$ .	(i) $y(n) = x(n^2)$ (ii) $y(t) = ax(t) + b$ . (10) A continuous time signal $x(t)$ is shown below. Sketch and label carefully each of the following signal :	Check whether the following systems are Linear/Non- Linear, Time Variant/Invariant, Static/Dynamic, Causal/ Non-causal and Stable/Unstable :	PART-B	Determine the Laplace Transform of $\delta(t - 3)$ . (1.5)	State any <i>two</i> properties of ROC of Laplace Transform. (1.5)	What is the ROC of z-transform for a finite duration anti-causal sequence? (1.5)	What is the relationship between DTFT and z-transform? (1.5)	What do you mean by aliasing? (1.5)	Find the Fourier Transform of a DC signal of amplitude 1. (1.5)	State the necessary and sufficient condition on impulse response for LTI system to be causal. (1.5)	(i) parallel (ii) series. (1.5)

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3.  $x(t) \cdot \left[ \delta\left(t - \frac{3}{2}\right) - \delta\left(t + \frac{3}{2}\right) \right]$ . 4. x(2t + 1).

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(a) Find the frequency response of a linear shift invariant

system whose input and output satisfy the difference

(c) Derive the expression for convolution sum if the input x[n] and impulse response h[n] is given. (5)

(b) Consider  $h[n] = \{1, 3, 2, -1, 1\}$  with origin at 3,

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and x[n] = u[n] - u[n - 3], determine the output y[n]

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of the LTI system?

y[n] - 0.5y[n - 1] = x[n] + 2x[n - 1] + x[n - 3].

equation :

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2. x(2-t).

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[P.T.O.

- 4 (a) Determine the circular convolution of two sequence  $x_1[n] = \{1, 2, 1, 0\}$  with  $x_2[n] = \{1, 0, 1, 1\}$ . (5)
- (b) State and prove the convolution property of DTFT.

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<u></u> Determine the Fourier Transform of the following : 3

(i) 
$$x(t) = sgn(t)$$
 (ii)  $x(t) = \cos w_0 t$ .

Ś (a) Using Laplace transform, find the impulse response of an LTI system described by the differential equation :

$$\frac{d^2y(t)}{dt^2} + 3\frac{dy(t)}{dt} + 2y(t) = x(t)$$

with all initial condition as zero.

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(b) Find the inverse Laplace transform of

$$X(s) = \frac{4}{(s+4)(s+2)}$$

if the ROC is :

$$-2 > Re[s] > -4$$

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ii) 
$$Re[s] > -2$$
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(iii) Re[s] < -4.

. (a) A Linear LTI system is characterized by the following

difference equation :

$$(n) - \frac{3}{2}y(n-1) + \frac{1}{2}y(n-2) = x(n), \quad n \ge 0$$

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Where  $x(n) = \left(\frac{1}{4}\right)^n u(n)$ 

(b) Determine the z-transform of  $x(n) = a^n \cos w_0 n u(n)$ . Subject to y(-1) = 4 and y(-2) = 10. Determine the Zero Input Response and Zero State Response. 8

- Find the condition for ROC also. Э
- (a) State and prove sampling theorem. છ

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- (b) Determine the Fourier Transform of  $x(t) = e^{-a|t|}$ . છ
- <u></u> Determine the z-transform and sketch the pole zero plot with the ROC for

$$x[n] = (0.5)^n u[n] - \left(\frac{1}{3}\right)^n u[n].$$
 (5)